Introduction

Myasthenia gravis (MG) is a relatively rare autoimmune disorder with different severities of muscle weakness. Although it can be life-threatening in some cases, MG is generally treatable and even curable with multidisciplinary treatments (1). In 1912, Schumacher and Roth first reported an improvement of myasthenic weakness after thymus removal for the treatment of thyrotoxicosis in an 18-year-old female patient (2). Later in 1939, Blalock et al. noticed a durable remission of generalized MG in a 24-year-old woman after thymectomy for the treatment of thymic cystic tumor (3). Two years later, Blalock described encouraging early results of six patients with MG after the removal of the thymus gland and recommended total thymectomy to alter the course of MG (4). Following these inspiring preliminary investigations, many surgeons performed numbers of observational retrospective studies to evaluate the role of thymectomy in the treatment of MG (5,6). In 2016, the first randomized controlled trial evaluating thymectomy in MG patients seropositive for anti-acetylcholine receptor (anti-AChR) autoantibody demonstrated that significant benefits in the improvement of neurological outcome and steroid-sparing effect favors extended transsternal thymectomy within a three-year follow-up (7). Recently, the 5-year results from MGTX still favor thymectomy for these
patients (8). It is now common knowledge that thymectomy is an indispensable and effective option for patients with MG.

The use of the da Vinci surgical system in thymectomy for the treatment of MG was first reported by Ashton et al. in 2003 (9). Since then many institutes have adopted robotic technology for thymectomy and reported their experience and clinical outcomes of patients undergoing robotic thymectomy for MG (10-13). Up to now, many approaches for robotic thymectomy have been developed and described, including unilateral, bilateral and subxiphoid (11,14-16). With the 3-dimensional (3-D) visualization, high dexterity and enhanced precision provided by the da Vinci surgical system, robotic thymectomy has been proved not only to be safe and feasible (17-21), but also to provide MG patients with encouraging neurological outcomes even comparing with the extended transternal thymectomy (19-21).

Although controversies exist as to the best approach for robotic thymectomy in the treatment of MG patients, we have been performing robotic thymectomy via a left-sided unilateral approach for MG patients since 2003 and consider it a perfect combination of minimal invasiveness and maximal exposure for resection. Furthermore, it could be shown that left-sided robotic extended thymectomy is significantly beneficial for MG patients according to cumulative complete remission comparing with non-robotic thoracoscopic thymectomy (21). Herein, we describe the left-sided robotic extended thymectomy for MG patients in detail, including patient selection and workup, preoperative preparation, equipment preference cart, procedure and tips, tricks and pitfalls.

**Patient selection and workup**

The main indications of robotic extended thymectomy for MG are patients with resectable thymomas or patients without thymomas aiming to reduce or avoid the use of immunosuppressive medications (22). The diagnosis of MG is usually confirmed by relevant symptoms and a positive test for antibodies against acetylcholine receptors (AChR), muscle-specific kinase (MuSK), and lipoprotein receptor-related protein 4 (LRP4) (23). If the antibodies are negative, neurophysiological tests and a Tensilon test would be performed to confirm the diagnosis (24). In anti-MuSK and anti-LRP4 MG patients, previous studies have shown that thymectomy has little effects on the improvement of MG symptoms if any (22,25). Although early removal of the thymus seems to be beneficial for MG patients (26,27), consensus and guidelines recommend that thymectomy should be performed after MG is well controlled to avoid postoperative respiratory failure (22,28).

Furthermore, a computed tomography (CT) scan of the chest should be performed in each MG patient before thymectomy, and if there is a mass with soft-tissue attenuation, contrast-enhanced CT will be performed to assess the enhancement characteristics and the adjacent structures of the lesion (29). If the lesion is adherent to adjacent tissues like major vessels, phrenic nerves or the sternum, the robotic extended thymectomy will not be suitable. In differentiating the hyperplasia from the thymoma, magnetic resonance imaging (MRI) can be better than CT, as thymoma may sometimes show diffuse thymic enlargement and may be diagnosed as hyperplasia in CT scan (30). Positron emission tomography-CT (PET-CT) can help to differentiate thymic cancer from other thymic diseases, but overlapping uptake value exists between normal and abnormal findings (31). Both MRI and PET-CT can be performed in need, but not routinely. In addition, pulmonary function tests and routine blood examinations for surgery as well as the electrocardiogram should also be used in the assessment of MG patients before the surgery.

**Preoperative preparation**

The position of the three trocars is usually marked on the skin for each case on the ward. Our usual approach for robotic extended thymectomy is performed through the left side under general anesthesia with a left-sided double-lumen endotracheal tube. Before the operation, the patient is placed supine and moved to the left edge of the operating table, the left arm is placed lower than the table plane, providing enough space for the motion of the instruments (Figure 1A). Thereafter, the operative field is prepared, sterilized and draped, exposing the adequate area to make sure a conversion to open or an introduction of a right-sided trocar could be easily performed if necessary (Figure 1B). Then, the 8mm trocar, to which the 30-degree robotic camera is mounted, is inserted at the 4th intercostal space on the midaxillary line, followed by insufflating carbon dioxide (CO2) to pressure about 8 mmHg. However, the insufflation of CO2 should be used only for the placement of the resting trocars or even be avoided if possible so that an exact incision of the mediastinal pleura can be performed. Subsequently, the 8mm cranial and caudal special working trocars are inserted at the 3rd intercostal space in the anterior axillary line and the 5th intercostal space between...
the anterior axillary line and the middle clavicular line respectively. The patient cart with four arms is docked on the right side of the patient (Figure 1C). The surgeon console is positioned at some distance from the patient while the vision cart is placed at the bottom of the operating table.

**Equipment preference cart**

Robotic extended thymectomy was performed initially with the basic model of the da Vinci system, later on refined accordingly with the development of the further models of the S-, and Si-system, and is actually performed with the da Vinci system Xi (Intuitive Surgical, Sunnyvale, CA), the fourth generation of the da Vinci system, which consists of a surgeon console, a patient cart with four robotic arms and a 3-D vision system. Comparing to the former Si and X generations, the Xi system has smaller, thinner arms, longer instrument shafts, allowing a greater range of motion and greater operational reach. Besides, the computerized automatic positioning system can help to shorten the docking process. Three robotic arms are connected with the surgical instruments, the middle one holding the camera, the cranial and the caudal ones connecting with an ultrasonic dissector and a precise bipolar forcep, respectively, they can wrist and rotate much more dexterously than human hands. The surgeon sits at the console with his fingers grasping the master controls to operate with extreme precision.

**Procedure**

We present here a complete process of robotic assisted thymectomy (Video 1).

The positioning of the trocars always follows a rule of measuring adapted to the very different anatomy of the patients and to the sternum. The initial use of CO₂-insufflation may be useful or even necessary at this point. The next step is the inspection of the thymic gland and the straight view at the left phrenic nerve with the 30° optic looking down. For MG patients with thymoma, meticulous inspection of the tumor is necessary before any dissection to re-check if the thymoma is adherent to any major vessels, nerves or adjacent organs. Furthermore, thoracoscopic exploration should be made to exclude or prove stage IV in thymoma cases. During the operation, the “no-touch” surgical technique should be obeyed to make sure the tumor is not directly manipulated, minimizing the risk of
tumor seeding. Furthermore, according to the International Thymic Malignancy Interest Group criteria (32), the surgical margins should be assessed by the pathologist with microscopic inspection after an en bloc resection of the thymus, thymoma and the mediastinal and lower cervical fat.

The dissection usually starts at approximately the middle of the pericardium along the left phrenic nerve where the thymus gland is regularly visible. In elder and/or obese cases where this area is frequently covered by fat tissue, the CO\textsubscript{2} insufflation can be applied to get a better view. There is always a gap between the upper part of the main thymic lobe – even if covered by large amounts of fat and the lower cardiophrenic fatty tissue.

The dissection is extended caudally along the left phrenic nerve until the phrenic bundle is isolated and the tissue in the aortopulmonary window is completely mobilized. Care should be taken of the left phrenic nerve while isolating, in some cases, the thymus gland can extend across the nerve or completely include the nerve. Dissection is continued upwards along the nerve until the cervical pleura is reached at the entrance to the innominate vein.

Then, the pleural incision is extended up to the jugular fold of the mediastinal pleura. Further dissection of the neck area at the left phrenic nerve allows for visualizing the innominate vein, regularly medial to the left phrenic nerve. Thereafter, the pressure of CO\textsubscript{2} can be increased to get a better view for the dissection of the neck area. However, attention should be paid to keep the right pleural cavity closed here, otherwise, the effect of CO\textsubscript{2} insufflation on enlarging the operative field will be lost.

The whole median retrosternal tissue is mobilized, then the right thymic lobe is visualized with surrounding fat tissue in the aortocaval groove. Then, the tissue in the left cardiophrenic angle is dissected and continue upwards. The last dissection proceeds from the left cardiophrenic angle to the subxiphoid area and extends to the right cardiophrenic area. The right pleura is opened at last and the cardiophrenic tissue is dissected completely.

In conclusion, the en bloc resected thymus specimen, including the mediastinal fat and thymoma (if any), is removed out in an endo bag through the camera incision. The whole specimen is weighed immediately after the removal, then is placed on a mediastinal board as in situ and photographed before sending it to the pathologists (Figure 2).

### Role of team members

The surgical team usually consisted of a board-certified console surgeon, a board-certified table surgeon, an anesthesiologist, a scrub nurse, and an operating room nurse. The console surgeon controlled the robot to perform an extended thymectomy. The table surgeon, on the left side of the patient, should excel at inserting the trocars and connecting, adjusting and changing the surgical instruments, also have a thorough knowledge of managing emergencies like major bleeding that may require a conversion to transsternal thymectomy. A scrub nurse should be familiar with the robotic materials and qualified for the adjustment and change of the robotic instruments. An operating room nurse should know how to connect and calibrate the robotic components. An experienced anesthesiologist in this team was supposed to be familiar with the management of both
robotic-assisted thoracic surgery and the general anesthesia in MG patients.

Each member of the robotic thymectomy team is crucial for the success of the robotic extended thymectomy. They should learn more than just professional knowledge but also be educated to be familiar with the da Vinci system, in case any technical problems occur during the procedure.

**Tips, tricks, and pitfalls**

The proper approach for robotic thymectomy has been an ongoing debate for decades among thoracic surgeons worldwide. Some surgeons supposed it was dangerous doing the left-sided approach for thymectomy, concerning about the indeed reports of cardiac injuries with trocar insertion. But this can be perfectly avoided by visual control guided the trocar insertion with scissors and adequate CO\(_2\) insufflation at the beginning. In fact, more than 900 cases have been performed in the Charité without any pericardium or heart injury during the placement of trocars. The insufflated CO\(_2\) can help to enlarge the space at the anterior mediastinum, providing adequate space for trocar placement. On the other hand, using stitch scissors with round tips to open the intercostal space by blunt dissection and to guide the insertion of the trocars can make sure the insertion is under control all the time. Furthermore, we have introduced this method into many institutes where the surgeons are doing quite well.

Another main reason why many surgeons favor the right-sided approach is that the visualization of the superior vena cava is beneficial for identifying the left innominate vein at the venous confluence. However, through the left-sided approach, the left innominate vein can also be easily identified after opening the cervical pleura fold at the point medial to the phrenic nerve. Before dissecting the upper poles from the inferior portion of the thyroid gland, grasping and pulling them downward is always necessary for a radical resection, and in this way, the overall anatomy of the left innominate vein is exposed, then identifying and dissecting the thymic veins which drain into the left innominate vein is followed without too much difficulty.

The authors prefer left-sided approach for robotic thymectomy, not only because the left lobe of the thymus is usually larger, but also because it is easy to handle the upper poles, manage the thymic veins, approach to the contralateral phrenic nerve and access the common anatomical locations with ectopic thymic tissue from the left side. The thymic tissue can extend to or even across the left phrenic nerve in many cases, which can hardly be addressed from the right side (33). Sometimes, the upper poles can hide behind or run circularly around the innominate vein, which is easier to manage through the left-sided approach. Besides, the left innominate vein mainly runs on the left side, which provides benefits for managing the thymic veins as well as protecting the innominate vein. Recently, our team did a close review on the presence of ectopic thymic tissue in patients undergoing thymectomy for MG (34), the results showed some preferred anatomical locations of ectopic thymic tissue: anterior mediastinal fat, pericardiophrenic angles, aortopulmonary window, cervical region (pretracheal fat) and lateral to phrenic nerves (mostly at the left side). Importantly, our previous study has shown that an extended thymectomy favors the left-sided approach (35).

During the last few years, subxiphoid robotic thymectomy has attracted increasing attention worldwide (16,36). This procedure offers surgeons a direct visualization of the mediastinum similar to median sternotomy in a minimally invasive way. Although the operative view of the neck region is good, when it comes to the anatomical variation of the upper poles running behind or even surround the innominate vein and ectopic thymic tissue

Figure 2 Specimen is placed on an ITMIG mediastinal board and photographed.
behind the left innominate vein, the left approach could be more direct. Besides, long-term follow-up data are needed to explicit the neurological outcomes of MG.

International consensus and guidelines recommend all MG patients with resectable thymoma undergo thymectomy after MG is well controlled, and thymectomy is performed for the treatment of thymoma with the resection of thymus and the mediastinal and lower cervical fat (22,28,37). Although many studies have shown robotic thymectomy is safe and feasible for MG patients with early-stage thymoma, the proper size of thymoma for robotic thymectomy and the long-term oncologic outcome after robotic thymectomy are still under debate (38-40). Available data has shown encouraging early and mid-term oncologic outcomes in MG patients with thymoma after robotic thymectomy (21,41). As for the proper size of thymoma for robotic thymectomy, although no international consensus or guideline is dictating the size of thymoma as a criterion for robotic thymectomy, most surgeons consider thymomas smaller than 5 cm are proper and acceptable for robotic thymectomy (38,42,43). However, recent studies have shown that robotic thymectomy is also safe and feasible for thymomas larger than 5 cm and the perioperative outcomes of patients are better when compared with open surgery (44,45). The authors also had some experience in handling large-sized thymomas in a robotic-assisted way, usually, a fourth trocar would be introduced at the subxiphoid to assist exposure and to take out the specimen. Thus, the authors recommend that robotic extended thymectomy is indicated in all patients with resectable thymoma, typically Masaoka Koga I and II.

High cost has long been considered as a pitfall for robotic surgery, also docking and undocking time needed for the relatively newly established team, especially when an emergency occurs. Since the console surgeon is not able to handle the emergency immediately due to the non-sterilized situation, there should always be an experienced surgeon sitting by the patient during the robotic surgery. Besides, conversion to open should be performed if major bleeding occurs or the oncologic principles (including incomplete resection, not en bloc resection or perforation of the capsule) are violated. Systemic training is needed for the whole team in the OR to avoid the unexpected accident, and a contingency plan should always be prepared before the robotic-assisted surgery.

Conclusions

The robotic approach is perfect for application to thymectomy, wherein the operative space is confined and the working angles are difficult for human hands. The left-sided robotic extended thymectomy is safe and feasible with encouraging clinical outcomes for both MG and thymoma. However, further researches with long-term follow up is still required before the robotic approach becomes the gold standard for thymectomy.

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Footnote

Conflicts of Interest: All authors have completed the ICMJE uniform disclosure form (available at http://dx.doi.org/10.21037/jovs.2020.03.08). JCR reports and declares as a proctor for Intuitive Surgical. The other authors have no conflicts of interest to declare.

Ethical Statement: The authors are accountable for all aspects of the work in ensuring that questions related to the accuracy or integrity of any part of the work are appropriately investigated and resolved. Written informed consent was obtained from the patient for publication of this manuscript and any accompanying images.

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