



Robotic substernal esophageal bypass and reconstruction with gastric conduit—frequently overlooked minimally invasive option

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Abstract: Modern esophagectomy includes the esophageal extirpation with immediate reconstruction of the gastrointestinal (GI) continuity via posterior mediastinal route. In the majority of cases tubularized stomach is chosen as the conduit of choice. Other conduits, such as colon or small bowel can be used for these purposes as well. In rare circumstances use of the alternative route for the conduit placement is required. Authors describe the technique of robotic substernal esophageal bypass and reconstruction of the esophageal continuity.

Keywords: Robotic esophagectomy; substernal reconstruction; substernal bypass; esophageal bypass; substernal gastric pull up; retrosternal reconstruction

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Overview

Esophagectomy is a complex surgical procedure most commonly performed for malignancy and sparingly for end-stage benign esophageal diseases. First esophagectomy have been performed and reported in 1913 by Franz Torek in New York (1). Since that initial experience numerous modifications of the procedure have been introduced into clinical practice. These procedures vary by the type of the surgical access, the extent of the resection, level of the anastomosis, type of the conduit and the placement route. Modern esophagectomy includes immediate reconstruction of the gastrointestinal tract continuity after resection of the esophagus. Recently popularized minimally invasive and robotic esophagectomy mimic standard well-established procedures, but convey improved outcomes due to decrease in morbidity and mortality of the esophagectomy (2-4).

Immediate reconstruction after esophagectomy most commonly utilizes posterior mediastinal (native) route for the placement of the conduit. This is currently a preferred

route for the conduit placement after esophagectomy. Despite decades-old conflicting data on the difference of the outcomes and the length of the route it has now been settled in all major esophageal centers (5). Previous anatomic studies demonstrated this route to be the shortest distance between abdomen and neck, requiring lesser length of the conduit for the reconstruction, potentially resulting in fewer complications (6,7).

The posterior mediastinal route has more normal, pseudo anatomical appearance. Perceived benefits of it are shorter distance and more normal anatomic appearance of the reconstruction, lesser incidence of the complications and lower mortality, better functional and cosmetic results and of course avoidance of additional field of surgical dissection for the extraanatomic placement (5,6,8-11). Despite that, it has some disadvantages. For example, there is an increased risk of conduit obstruction and recurrent dysphagia in cases of incomplete resection or local recurrence (12). On the contrary, retrosternal route potentially offers advantages of

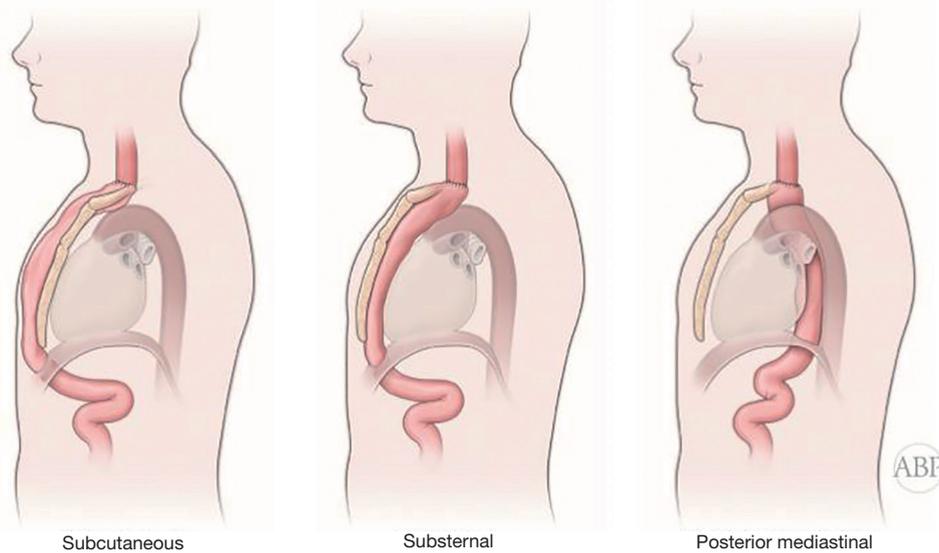


Figure 1 Alternative routes of conduit placement for esophageal reconstruction.

avoiding dysphagia in these circumstances, spares conduit from the radiation field, avoids development of hiatal/paraconduit hernia and is a route of choice for staged or delayed reconstruction (11,13).

Multitude of studies have demonstrated posterior mediastinal being shorter than retrosternal route (14,15). However, several publications have disputed that data (7,16,17). Substernal route results in two significant angulations of the conduit on its course—one at the cervical level, where the esophageal stump is brought from prevertebral position through the thoracic inlet to the superficial retrosternal position. Second bend occurs at the level of the diaphragm, where the conduit again deviates posteriorly to reach the stomach, pylorus and eventually retroperitoneal location of the duodenum (*Figure 1*). These angulations can potentially impair transit of the food bolus in already aperistaltic conduit, contributing to swallowing difficulties and dysphagia and can potentially complicate endoscopy and dilations postoperatively (10,18). In addition, previous sternotomy with open heart surgery significantly complicates dissection and conduit placement. Retrosternal conduit in turn will compromise surgical access in cases of cardiac procedure in the future (19–21). For these reasons routine retrosternal conduit placement is currently avoided (9).

Occasionally, extraanatomic route is required for reconstruction of the esophageal continuity. Multitude of the extra-anatomic routes have been described, such as retrosternal (substernal), presternal (subcutaneous),

transpleural (retro- and antehilar) (*Figure 1*). Transpleural routes are essentially modification of the posterior mediastinal bed with violation of the mediastinal pleura. With wide opening of the mediastinal pleura in Ivor Lewis and McKeown modifications, conduit is essentially prolapsing into the right pleural space (*Figure 2*). Presternal/subcutaneous route confers poor cosmetic results, leads to development of epigastric incisional hernia and poor functional outcomes and currently is rarely used (22,23). It has, however, been advocated as the choice of reconstruction in frail patients, sometimes as the two staged approaches (24,25). Out of the multitude of the extraanatomic routes for esophageal reconstruction, the largest experience is accumulated with retrosternal placement of the conduit (9,12,26–31).

Use of extra anatomic route can be justified in cases of unsuitable native esophageal bed for conduit placement. This is frequently the case in delayed reconstruction. Esophageal exclusion with the diverting esophagectomy can be performed as a salvage procedure for the control of mediastinal contamination in cases of uncontrolled esophageal leak, esophageal perforation or conduit, unusable for the reconstruction (9,32–34). This devastating scenario can be a complication of the previous esophageal surgery. Conduit necrosis with anastomotic leak after esophagectomy, leak after procedures for the benign foregut problems, such as paraesophageal hernia, achalasia and others can demand esophageal diversion, once conservative therapy and all endoscopic interventions to control the

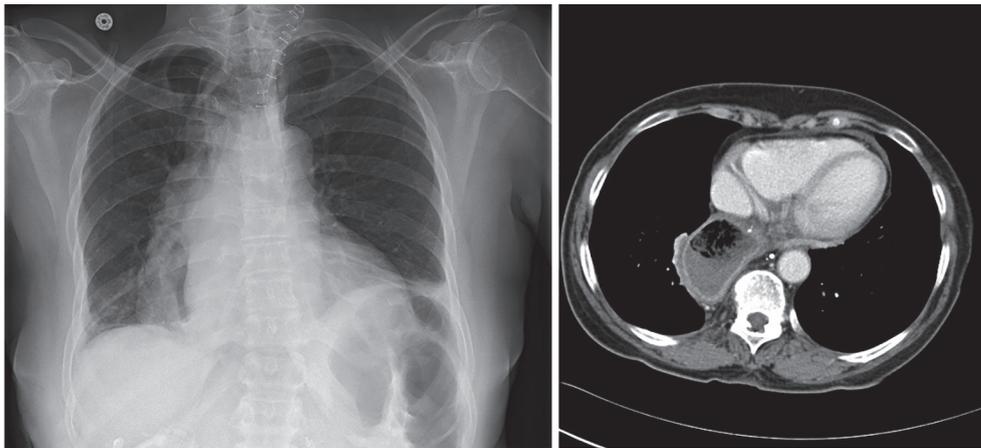


Figure 2 Chest X-ray (CXR) and computed tomography of a patient after McKeown esophagectomy. Prolapse of the conduit into right pleural space is evident.

leak ultimately fail. This also might be required in cases of esophageal perforation, iatrogenic or spontaneous, especially with delayed presentation. Patients, surviving this devastating complication are desperately seeking restoration of the esophageal continuity for resumption of the oral intake and quality of life improvement (32,35,36).

Multiple studies demonstrated increased rates of complications and postoperative mortality in patients, undergoing retrosternal reconstruction after esophagectomy (5,8,17,18,29,37-39). However, in metaanalysis there was no difference in outcomes (31). Some experts propose delay in the anastomosis creation after delivering gastric conduit to the neck by several weeks. In delayed esophagogastrostomy well perfused conduit, no leaks, wound infection or sepsis with very few patients developing anastomotic strictures, requiring intervention were observed (40,41).

Retrosternal bypass with either gastric or colonic conduit had been used in the past for palliation of the dysphagia in cases of locally advanced unresectable esophageal cancer, frequently complicated by tracheoesophageal fistula (26,29,42). However, due to high morbidity and mortality this morbid procedure has all but disappeared from the clinical practice. This process has been facilitated by development of other, less dramatic palliative options—chemotherapy, radiation therapy and endoluminal palliation techniques, such as photodynamic therapy (PDT), brachytherapy, laser and cryoablation and self-expandable stents (43-48). Leaders in the field have condemned surgical esophageal bypass as ill-advised due to high rate of morbidity and mortality (37,49).

Malignant esophageal to airway fistulas leads to

uncontrolled airway soilage, pneumonia, severe sepsis and is complicated by high rates of mortality (35). Esophageal bypass has been demonstrated to control soilage and palliate symptoms, again at the cost of significant surgical morbidity and mortality (42).

In pediatric population substernal colon interposition had been used for reconstruction of esophageal atresia with tracheoesophageal fistulas. Long term functional outcomes had been satisfactory with adequate growth of the patient (27,50).

In cases of caustic esophageal injury patients develop severe fibrotic reaction and long recalcitrant strictures. Substernal bypass had been utilized with success in this challenging patient population. Frequently, native esophagus had been left intact due to challenges of dissection in severely fibrotic mediastinum (23,51,52). However, due to increased risk of malignancy many authors propose removal of the diseased esophagus with substernal reconstruction (53).

Minimally invasive, and especially robotic surgery, has been demonstrated to improve outcomes with decreased morbidity, mortality, length of stay and postoperative recovery (2,3,54). For this reason, it has seen rapid adoption into the field of complex esophageal surgery (4,55,56). Minimally invasive and robotic techniques of substernal esophageal reconstruction have been successfully reported in recent literature (55,57,58). With increasing complexity of robotic esophageal procedures routinely performed in the clinical practice, practicing surgeons need to be aware of such advanced reconstructive options as retrosternal bypass and gastric conduit reconstruction.



Figure 3 Bronchial blocker lung isolation.

Authors experience

Authors have performed robotic substernal esophageal bypass and reconstruction in four cases.

A 63-year-old male patient during attempted resection of esophageal adenocarcinoma developed intraoperative bleeding with hemorrhagic shock, complicated by pneumonia and septic shock, forcing surgeon to avoid immediate reconstruction and resort to diversion esophagostomy. After successful recovery patient was brought for retrosternal reconstruction 3 months postoperatively. Procedure was complicated by anastomotic leak, resolving with conservative management and endoluminal VAC therapy within a month with restoration of oral nutrition.

A 71-year-old female patient was transferred from outside facility in shock due to esophageal perforation and leak after minimally invasive repair of paraesophageal hernia. Patient underwent esophageal diversion for control of the source of sepsis. After successful recovery patient underwent reconstruction of gastrointestinal (GI) continuity via substernal gastric conduit reconstruction 4 months after diversion. She has recovered well without leak and full restoration of oral nutrition.

A 42-year-old male, presented in sepsis with pneumonia due to malignant bronchoesophageal fistula due to esophageal squamous cell carcinoma, failed to control with covered esophageal stent. After medical optimization with parenteral nutrition and antibioticotherapy, patient underwent substernal gastric conduit esophageal bypass. After prolonged ICU and hospital course patient has restored oral nutrition and underwent palliative

chemotherapy with concurrent radiation therapy with no evidence of disease 2 years after procedure

A 46-year-old male with a history of idiopathic thrombocytopenic purpura (ITP), bilateral above-the-knee amputations (AKA), sepsis, ischemic esophagitis with recalcitrant esophageal stricture developed a bronchoesophageal fistula, failed to control with the stenting, requiring diverting esophagostomy. After medical optimization, 7 months later, the patient underwent robotic retrosternal gastric conduit reconstruction. Postoperative course was complicated by leak, resolving with restoration of oral nutrition 2 months postoperatively.

Technical steps of the substernal reconstruction

Equipment and supplies

We recommend performing esophagectomies on DaVinci Xi surgical platform. It offers several advantages, including beam rotation, allowing docking on either side of the table, camera hopping between ports, wide range of motion, extended length of the instruments, simultaneous use of energy in multiple instruments and lesser spacing between the ports. Whereas surgeon is forced to perform procedure on the Si platform, adjustments to accommodate some of the shortcomings of the older platform are necessary. With progress of the technology and ongoing upgrades of the BaVinci robots in practice, it is expected to see gradual replacement of Si model with time.

Anesthesia and patient setup

Procedure is performed under general endotracheal anesthesia. Abdominal and substernal part of the procedure is performed under single lumen anesthesia. Most of the time this procedure is performed for reconstruction of previous esophageal diversion. As such, in the majority of cases esophageal resection had been completed previously. When thoracic part is planned for esophageal resection, such as esophageal exclusion in tracheoesophageal fistula, standard lateral position of the patient and docking is required. In these cases, we strongly prefer bronchial blocker for the purpose of lung isolation (*Figure 3*). Its lower profile and rigidity provide easier and safer dissection of the cervical esophagus. At the end of the case it allows simple conversion to single lumen by removal of the blocker, avoiding potentially dangerous reintubation for toilet bronchoscopy or in case of prolonged ventilation.

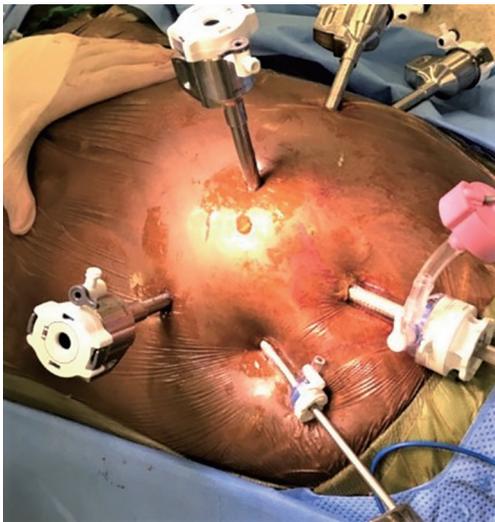


Figure 4 Positioning of the patient.



Figure 5 Jell roll under the left flank facilitates partial rotation of the patient to the right.



Figure 6 Cervicotomy incision with extension on the manubrium with dissection of the esophagostomy stamp.

Steps of the procedure

Intraoperative endoscopy

After intubation, on-table endoscopy is performed to define the anatomy. In cases of delayed reconstruction after previous cervical esophagostomy, the esophageal stump needs to be assessed for usability and margins. In the cases of planned palliative resection or esophageal bypass,



Figure 7 Substernal gastric conduit reconstruction (59).
Available online: <http://www.asvide.com/article/view/31470>

careful assessment of the anatomy is required. Assessment of the stomach is rarely possible as it is either previously disconnected in cases of diversion esophagostomy or might not be accessible due to high grade stricture or malignancy. Review of cross-sectional imaging or previous endoscopy is paramount.

Colonic conduit requires preoperative colonoscopy to assure absence of pathology, precluding its use as a conduit.

Patient positioning

Patient is positioned supine (*Figure 4*). Shoulder roll is placed for neck hyperextension. Head is rotated to the right for left cervicotomy and esophageal dissection. The right arm is abducted, and the left arm is tucked along the body. Gel roll under the left flank provides slight rotation of the patient facilitating intraabdominal exposure (*Figure 5*). Wide surgical field prep is applied including neck, chest and abdomen.

Cervicotomy, thoracic inlet enlargement and dissection of the esophagus

Initial dissection of the neck is started prior to docking of the robot for abdominal part to have a free unobstructed access to the neck. Oblique incision is created along anterior border of left sternocleidomastoid muscle with the extension onto the manubrium (*Figure 6* and *Figure 7*, 00:08). Dissection is carried medial to carotid sheath until prevertebral fascia is encountered and retroesophageal space is exposed. Thyroid laryngeal complex is rotated medially. Attention should be paid to the integrity of the recurrent laryngeal nerve and contact with it should be maximally avoided. Use of self-retaining metal retractors is not recommended for this reason.

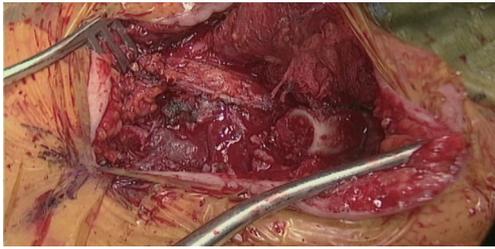


Figure 8 Resection of the left sternoclavicular joint.



Figure 9 Resected specimen of left sternoclavicular junction (SCJ).

In patients with previous diversion, the esophagostomy is dissected from the skin and the stump is delivered into the cervicotomy wound (*Figure 6*). In case of bypass, the esophagus is mobilized with blunt dissection from the membranous portion of the trachea. Dissection is carried maximally distally into the posterior mediastinum and esophagus is divided with TA-stapler. If thoracic mobilization was performed during thoracic part for esophageal resection, Penrose drain, placed into the thoracic inlet helps with dissection and delivering the esophageal stump into the wound.

In order to avoid conduit compression with retrosternal route, enlargement of the thoracic inlet aperture is required. Partial left manubriectomy with distal claviclectomy and first rib resection is required for this purpose (*Figure 7*, 00:24; *Figure 8*). After opening of the interclavicular ligament, retrosternal space is developed with blunt digital dissection. The heads of the sternocleidomastoid muscle (SCM) are mobilized off the manubrium and distal clavicle. Left pectoralis major muscle is raised off the sternum. Intercostal

muscle of the first interspace is mobilized of the manubrium. Attention is paid to avoid left internal mammary pedicle. With the use of the sternal or oscillating saw manubrium is divided at the midline to the lower level of the first intercostal space. Horizontal manubriotomy is performed from the left lateral aspect of the manubrium at the first intercostal space to meet the vertical cut at the midline. Distal clavicle is encircled with right angle clamp and divided with Gigli saw approximately an inch lateral to the SCJ. Underlying first rib is divided at its cartilaginous portion with rib cutter (*Figure 9*). With blunt digital dissection tunnel is created distally over the pericardium and is packed with surgical gauze for hemostasis, pending transabdominal dissection.

Abdominal port placement

Abdominal part of the procedure is started simultaneously with cervicotomy, pending docking of the robot until completion of the later. Equipment and supplies for the procedure are listed in *Table 1*. Access to the peritoneal cavity is gained in left periumbilical area with either Veress needle or 5 mm optical trocar. 15 mm of carboxy pneumoperitoneum is created. The robotic camera port is placed in the left paramedian area, 8 cm above the umbilicus. Standard 8 mm robotic ports are placed under the costal margin at the left anterior axillary line, left mid-clavicular and at the right mid clavicular line. In case of use of robotic stapler left arm port is replaced with 12 mm robotic port. The 5-mm port is placed in the right flank and a Mediflex® (Islandia, NY, USA) retractor is used for liver elevation. Nathanson retractor can help localize sternal part of the diaphragm prior to tunnel dissection. Assistant 12 mm laparoscopic port is placed in periumbilical area.

The patient is placed in a reverse Trendelenburg position, and the robot is docked (*Figure 10*). A 30-degree down camera is used. Bipolar Cadiere grasper is used in arm 1, vessel sealer in arm 3 and a tip up grasper in arm 4.

If enteral access has been established previously it may interfere with port placement. In case of gastrostomy, ports need to be placed below for its dissection and take down. To control the spillage, gastric wall defect can be over sewn or closed with the linear stapler. This defect preferably to be excluded from the conduit during stapling.

Jejunostomy can be preserved for postoperative enteral access and left-flank ports must be placed above and medial to it to avoid interference with range of motion and manipulation.

Table 1 List of instruments and supplies for the DaVinci Xi robotic substernal reconstruction

Robotic equipment
DaVinci Xi platform
Four 8-mm ports
12 mm port (for robotic stapling)
30- and 0-degree cameras
Cadiere bipolar grasper
Vessel sealer
Tip-up grasper
Robotic stapler
Robotic needle driver
Robotic scissors
Laparoscopic instruments
Laparoscopic tower
5-mm 0- and 30-degree cameras
Veress needle or 5 mm optical port
12-mm assistant port
Mediflex liver retractor with bed mount
Laparoscopic suction irrigator
Laparoscopic grasper
Laparoscopic scissors
Endo Stitch™ device with #2-0 Ethibond sutures
Laparoscopic linear stapler
Other supplies
Gigli saw
Sternal or oscillating saw
Rib cutter and rongeur
Skin stapler
14-Fr jejunostomy tube with introducer kit
Silk #1 and # 2-0
Vicryl #2-0
Prolene #2-0
½ inch Penrose drain
TA stapler



Figure 10 Docking of the DaVinci Xi robot.

Gastric dissection and conduit preparation

Dissection of the stomach and preparation of the conduit starts with hiatus inspection. In case of previous diversion, gastro esophageal junction (GEJ) is divided and hiatus is closed. Some lysis of adhesions in this area might be required (*Figure 7*, 00:49). Otherwise the stomach is retracted laterally and pars flaccida of the gastrohepatic ligament is opened with the vessel sealer, exposing the right crus of the diaphragm. The phrenoesophageal membrane is opened circumferentially and high mediastinal dissection and mobilization of the esophagus is performed. Esophagus is divided with the linear stapler as proximally as possible and is delivered into the abdomen. Prior to the esophageal division, nasogastric tube, if present, is pulled back above the level of transection. If thoracic part was performed, the Penrose drain, positioned around distal esophagus helps with the hiatal dissection.

At this point the stomach is retracted medially and cranially and gastrocolic ligament is splayed with lateral traction. With the use of the vessel sealer, the gastrocolic ligament is divided over the mid-body, carefully preserving the integrity of the gastroepiploic pedicle. Complete mobilization of the greater curvature is performed (*Figure 11*). An omental flap, based on the short gastric vessels in the mid-body, can be harvested for coverage of the gastroesophageal anastomosis.

The stomach is retracted laterally and left gastric pedicle is exposed with dissection of the lymphatic tissue toward the specimen in oncologic cases. Either robotic vascular-load

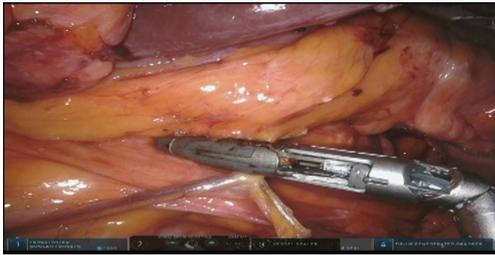


Figure 11 Mobilization of greater curvature.



Figure 12 Division of the left gastric pedicle.

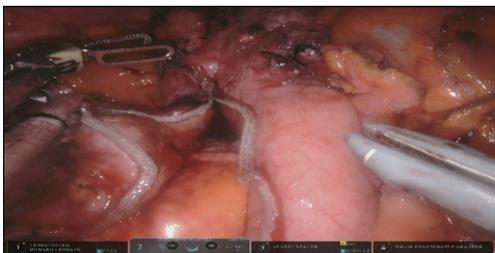


Figure 13 Preparation of narrow gastric conduit.



Figure 14 Pyloromyotomy.

stapler passed through the left subcostal port or standard linear stapler through the assistant port is used for division of the left gastric pedicle (*Figure 7*, 02:08; *Figure 12*).

The gastric antrum is retracted medially for the Kocher maneuver and lateral attachments of the duodenum are



Figure 15 Closure of the hiatus.

divided. Adhesions from previous cholecystectomy can present a challenge and need to be mobilized as well. Upon completion of the dissection the pylorus should be easily reaching to the level of hiatus.

Narrow gastric conduit is created by sequential stapling of the stomach along the greater curvature (*Figure 7*, 02:53; *Figure 13*). Stomach is splayed by applying traction laterally and cranially at the fundus and laterally and caudally at the antrum. Starting at the incisura with the linear stapler approximately 5-cm wide gastric tube is fashioned. Attention should be paid to avoid spiraling of the conduit or folding of the posterior gastric wall, by perfect orientation of the retracting arms and the stapler.

Pyloric drainage

Use of robotic technology allows precise dissection of the duodenal wall layers and performance of a true pyloromyotomy in the majority of cases. Seromuscular 2-0 silk stitch is placed across the pylorus and muscle fibers are divided over the stitch. Remaining muscular fibers are divided until free bulging mucosa is achieved (*Figure 14*). Pyloromyotomy is closed in transverse Heineke-Mikulicz fashion (*Figure 7*, 02:30).

Closure of the hiatus

Substernal reconstruction, placing the conduit into the anterior mediastinum calls for complete closure of the hiatus to prevent complications, associated with hernia formation. Hiatus is closed with interrupted #1 silk sutures. Pledges can be used for tissue reinforcement. Usually 4 to 5 sutures are required for complete closure (*Figure 15*).

Dissection of the substernal tunnel

The camera is switched to 30-degree up position. Utilizing Veress needle as a finder probe, sternal part of the diaphragm is identified by advancing the needle at the tip of xyphoid

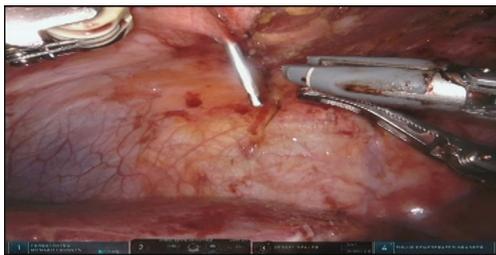


Figure 16 Localization of the sternal part of the diaphragm with Veress needle.



Figure 17 Substernal tunnel dissection. Please note surgeon's finger visible in the tunnel, advanced from the cervicotomy wound.

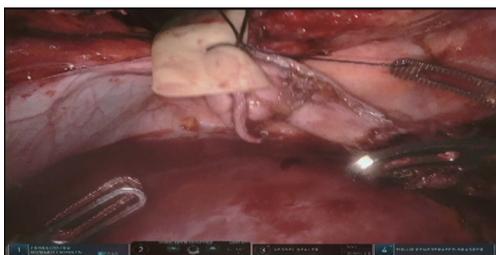


Figure 18 Extraction of the specimen, secured to the Penrose drain.



Figure 19 Delivery of the conduit into the tunnel.



Figure 20 Securing of the conduit to the edge of the diaphragmatic defect.

process (*Figure 7, 03:43; Figure 16*). While retracting sternal part of the diaphragm it is opened with the vessel sealer for approximately 5 cm parallel to the sternum. Alternating blunt and sharp dissection the retrosternal tunnel is created over the anterior pericardium, meeting the dissection plane from the neck (*Figure 7, 04:24; Figure 17*).

Placement of the conduit

Specimen is extracted through the tunnel after being secured to the Penrose drain, advanced from the cervicotomy (*Figure 7, 05:17; Figure 18*).

Penrose drain is advanced back through the neck wound into the tunnel, grasped and delivered into the abdomen. Conduit is secured to the drain with two stitches and delivered into the neck incision under visual control from the abdomen to assure proper alignment (*Figure 7, 05:41; Figure 19*). Additional mobilization of the conduit might be undertaken at this point if required. The conduit is secured to the edge of the diaphragmatic defect to relieve the tension and prevent hernia formation (*Figure 20*).

Cervical anastomosis

We prefer fully mechanical linear stapler anastomosis in the neck. Conduit is pulled until proper tension to avoid redundancy. Esophageal stump and the tip of the conduit are aligned and the posterior wall stitch is applied. Thick 60 mm linear stapler cartridge is advanced into both lumens and fired, creating anastomosis (*Figure 7, 06:16; Figure 21*). Naso gastric tube (NGT) is advanced into the distal conduit under direct vision. Anterior aspect of the anastomosis is completed by horizontally firing liner stapler, closing the lumen (*Figure 22*). Jackson-Pratt drain is placed along the anastomosis and brought out through a separate stab incision. Wound is closed with restoration of the muscular layer



Figure 21 Cervical anastomosis with the linear stapler.

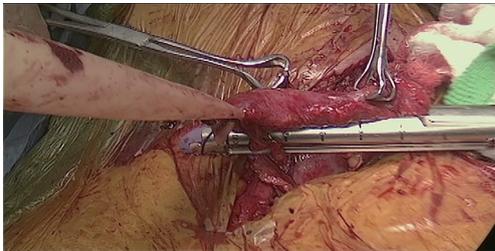


Figure 22 Closure of the anastomotic lumen with the linear stapler.

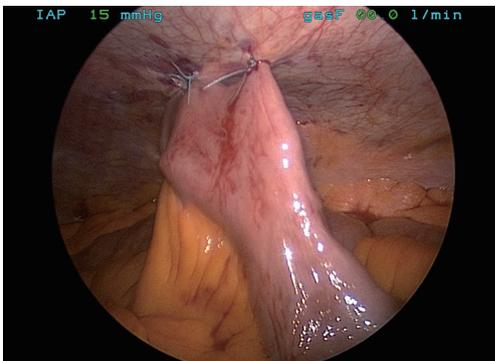


Figure 23 Jejunostomy.

between SCM, pectoralis major and contralateral muscles. Skin is closed with staples.

Enteral access

If not previously established, jejunostomy is performed at this point in the preferred fashion. Since placement of the jejunostomy will require redocking of the robot we perform it mainly laparoscopically. Right subcostal, right flank, and assistant ports are used. Ligament of Treitz is identified by elevating colon cranially. Thirty to 50 cm distally loop of small bowel is secured to the abdominal wall in the left flank. With the use an introducer kit a 14 Fr. jejunostomy



Figure 24 Postoperative esophagram in patient with substernal gastric reconstruction.

tube is placed into the lumen. A half-purse-string and an antitorsion stitches are applied (*Figure 23*).

Postoperative management

Standard length of hospital stay after robotic esophagectomy is 5 to 7 days. Substernal reconstruction in the open literature was associated with higher rate of morbidity and length of stay. Close monitoring for development of postoperative complications is mandatory. Patient general status, signs of sepsis, quality and quantity of drain output and airleak are inspected frequently. Pressors are avoided intraoperatively and in the postoperative period to avoid compromise of tenuous conduit blood supply. Enteral nutrition is started on postoperative day 2 and advanced as tolerated. Rehabilitation with physical therapy is started on postoperative day (POD) 1. Esophagram with water-soluble contrast and thin barium is performed prior to discharge (*Figure 24*). Prior to initiation of the oral nutrition speech language pathologist and video barium swallow is recommended to rule out aspirations (*Figure 7, 06:45*). If anastomotic leak occurs, majority can be managed by opening of the cervical wound for drainage. Endoluminal vacuum assisted closure (VAC) therapy has been shown to hold promise in the management of the leaks. Due to high level of anastomosis and angulation at the level of thoracic inlet we avoid using stent for the management of leaks.

Postoperative surveillance is performed with cross-sectional imaging in cases of malignancy according to the stage of the disease and practice guidelines (*Figure 7, 06:59; Figure 25*).

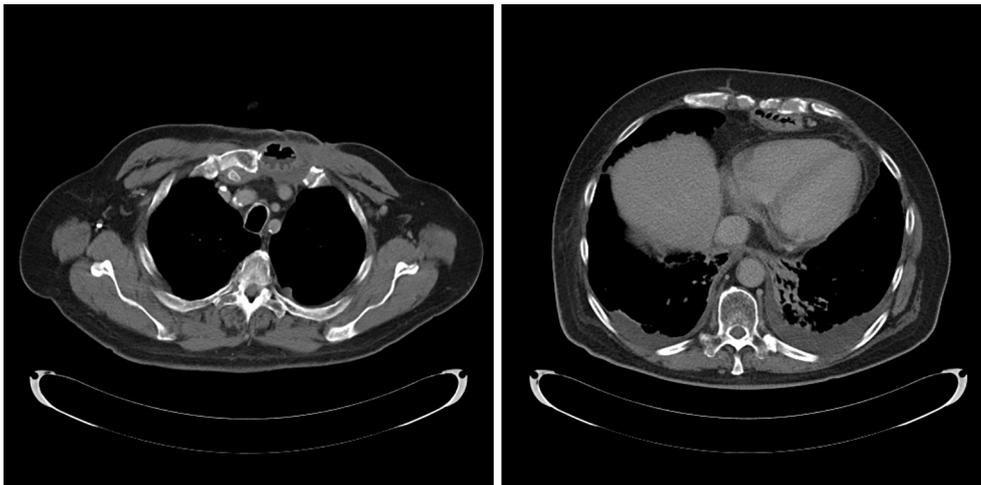


Figure 25 Surveillance computed tomography of the patient after substernal reconstruction.

Conclusions

In summary, substernal reconstruction is a rare procedure that can be utilized in difficult scenarios for this select group of patients. Robotic technology is feasible, potentially decreasing morbidity of this complex procedure. Surgeons with the interest in complex esophageal procedures should have it in their armamentarium for the best patients' outcomes.

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